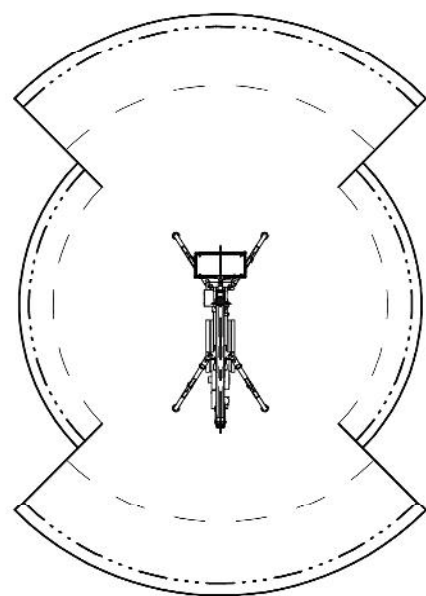
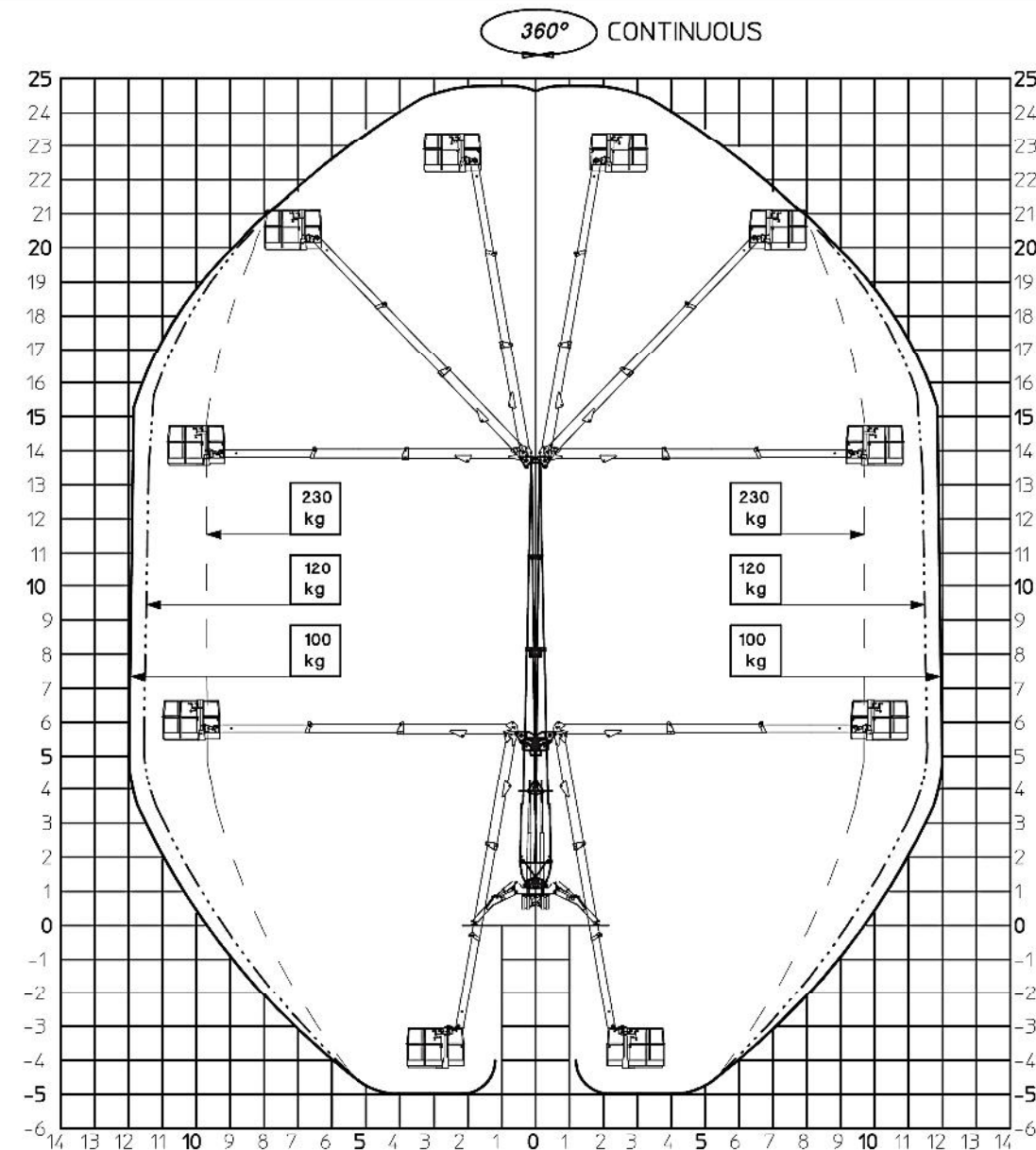
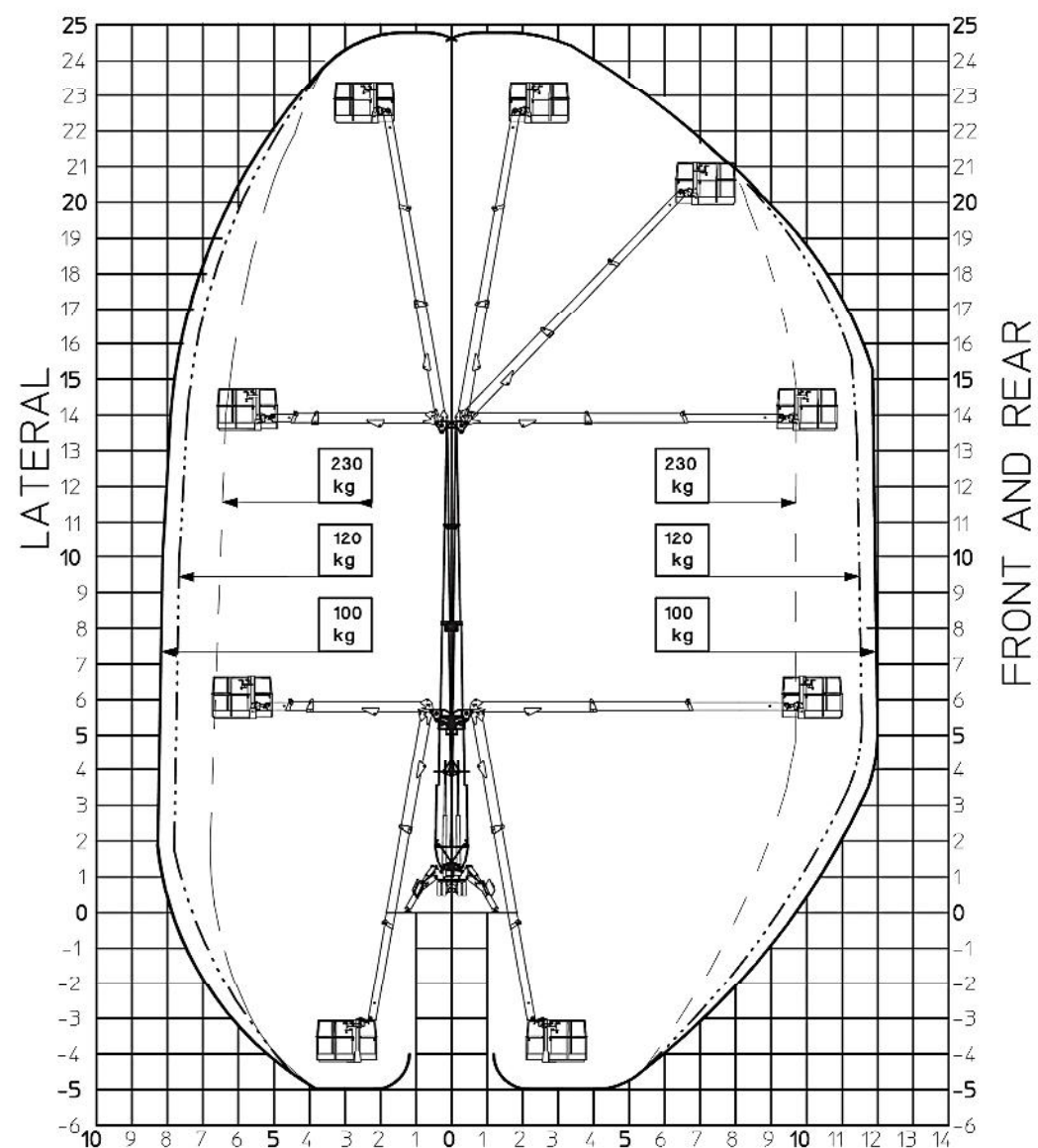
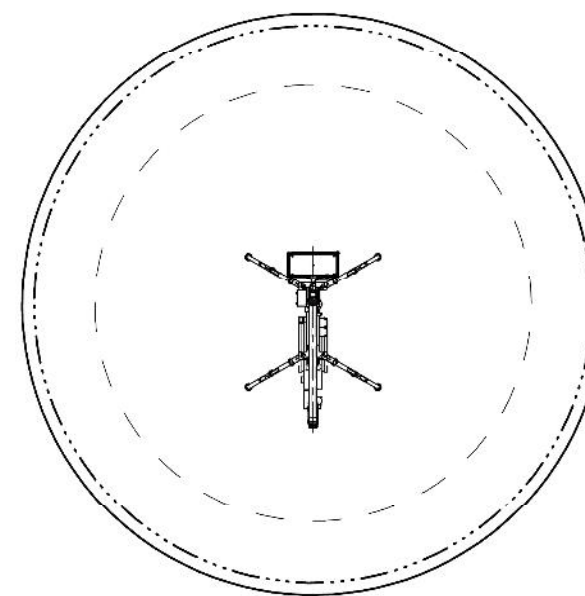




PORTATE

- — — — — = 100 kg
- · — · — · — = 120 kg
- — — — — = 230 kg



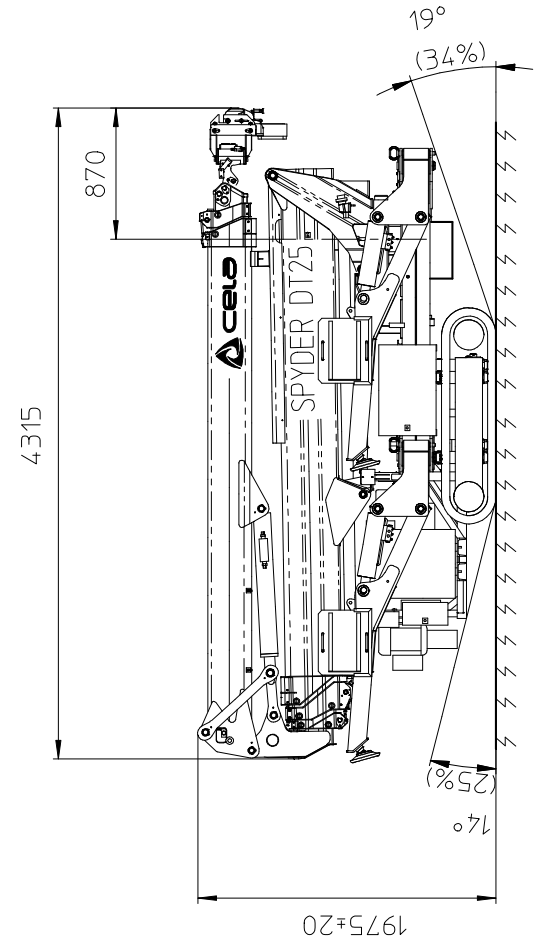
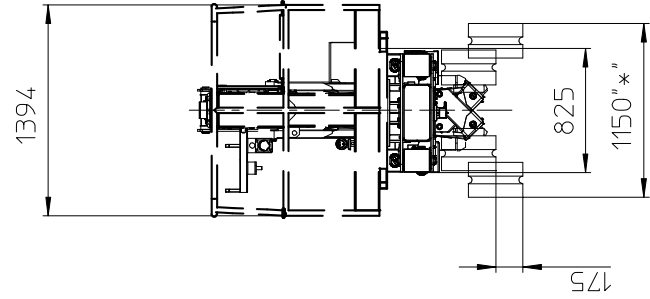
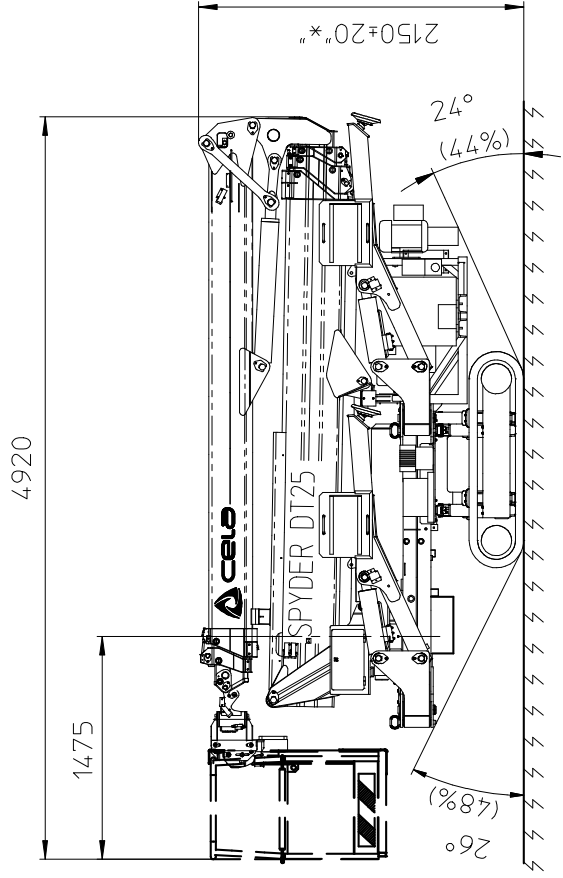
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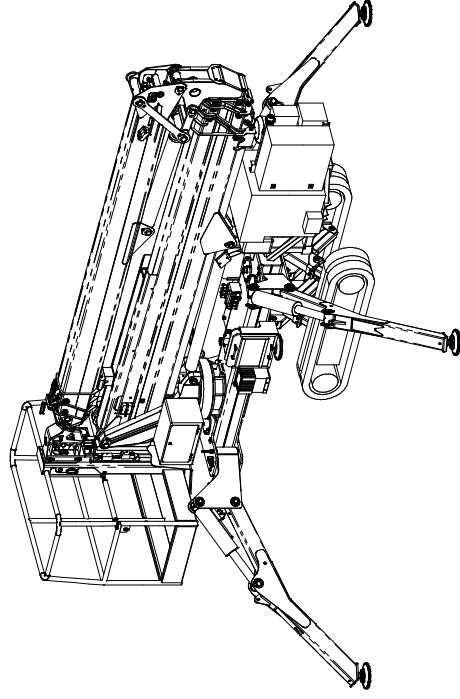
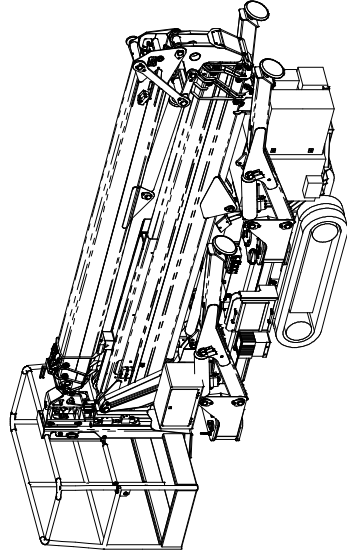
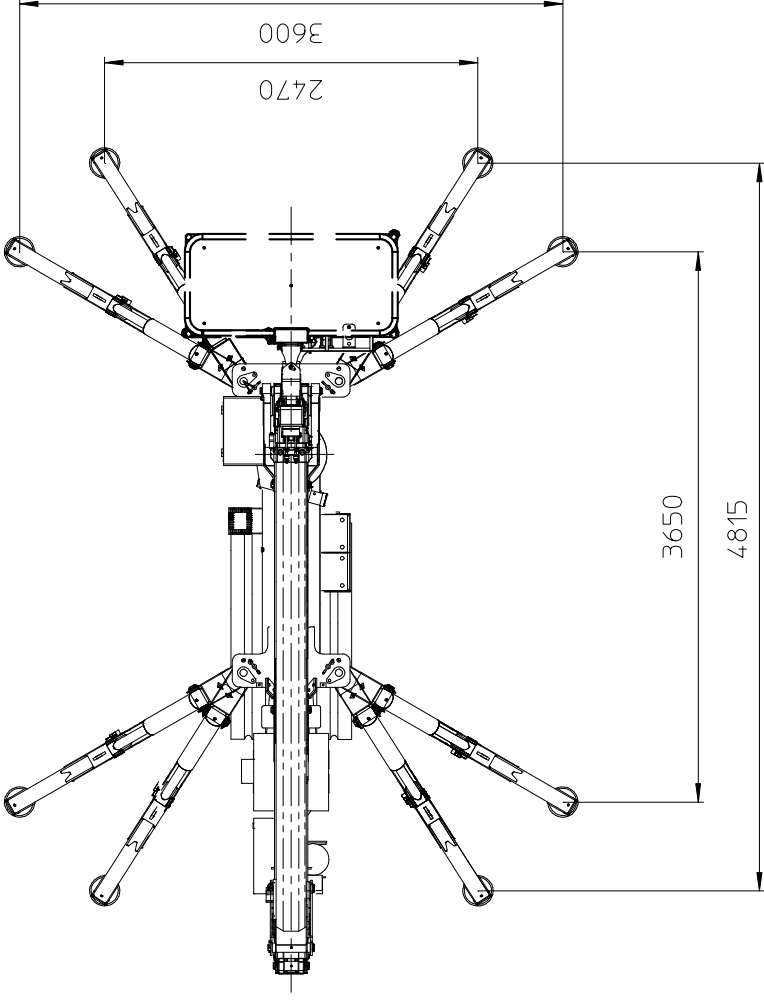
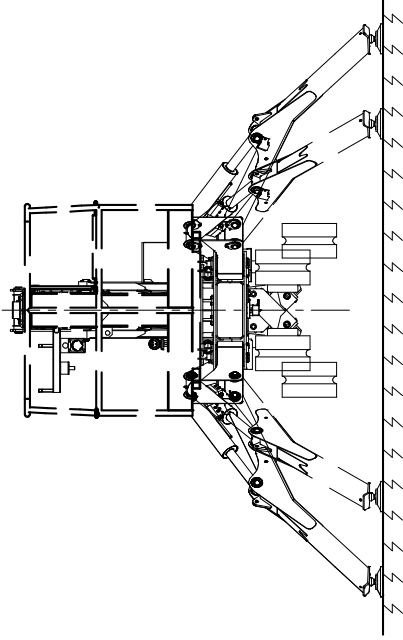
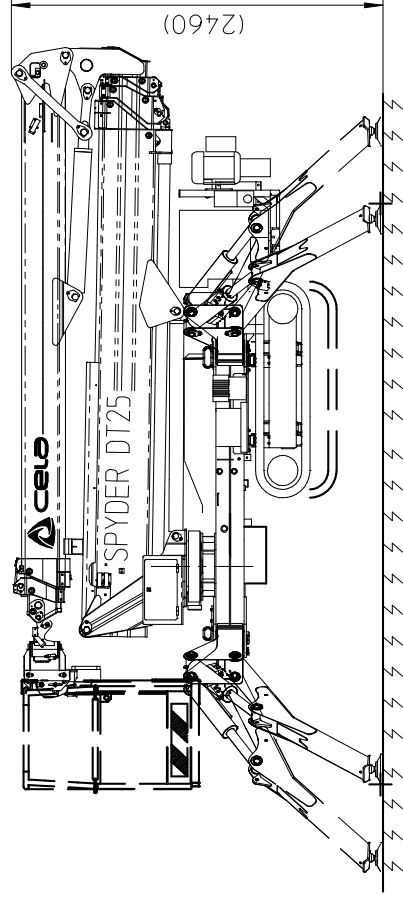
PROVISIONAL



DENOMINAZIONE - NAME	WORKING AREA	DISEGNATO - DRAWN	CONTROLLATO - CHECKED
VEICOLO - CHASSIS	-	R.F.	T.S.
PIATTAFORMA - PLATFORM MODEL	DT25 SPYDER	P.T.T. - G.V.W.	1005701
	2.95 T.	AREA DI LAVORO - WORKING AREA	1005702



"*" = gruppo cingolo aperto
"*" = opened track crawler



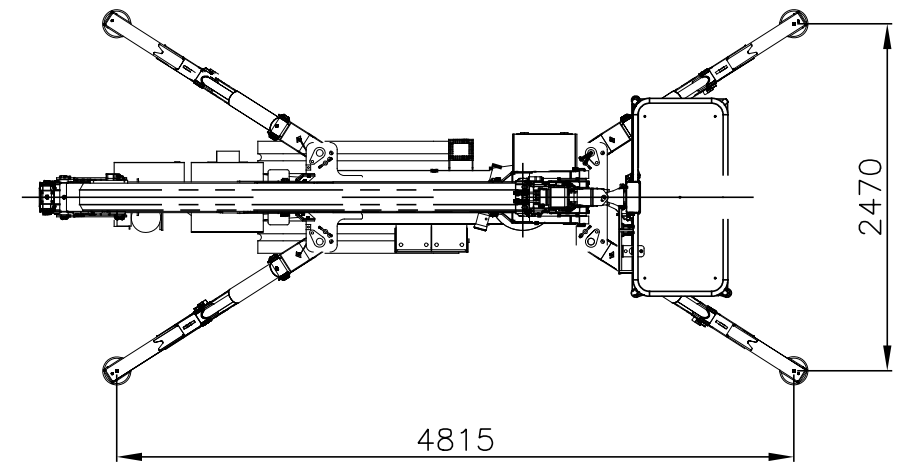
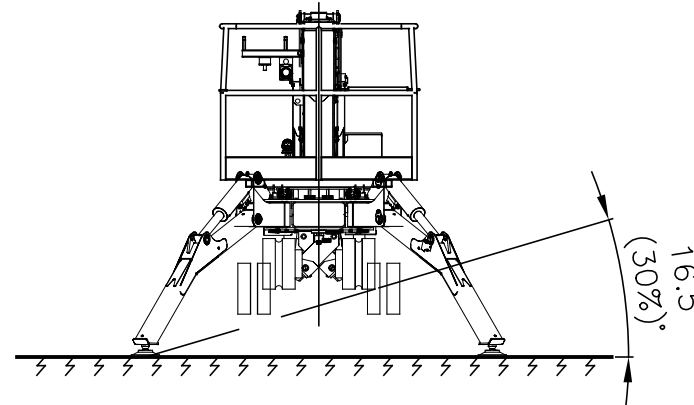
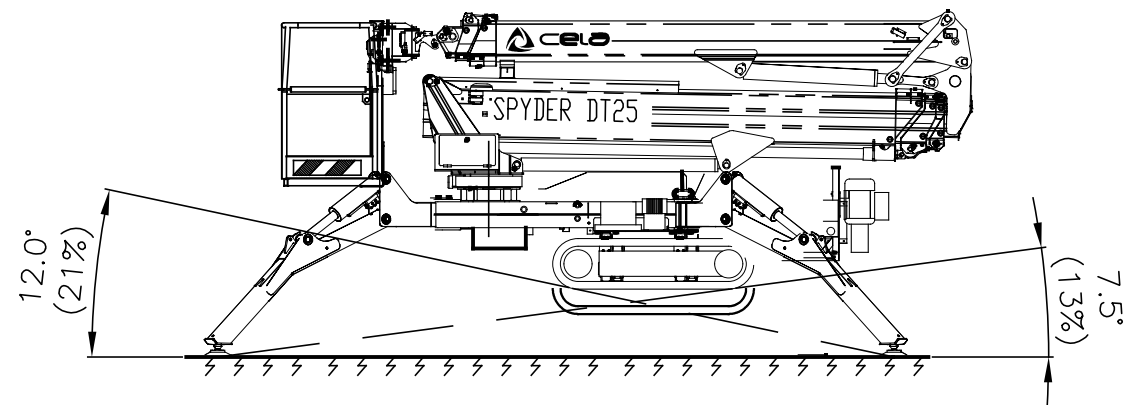
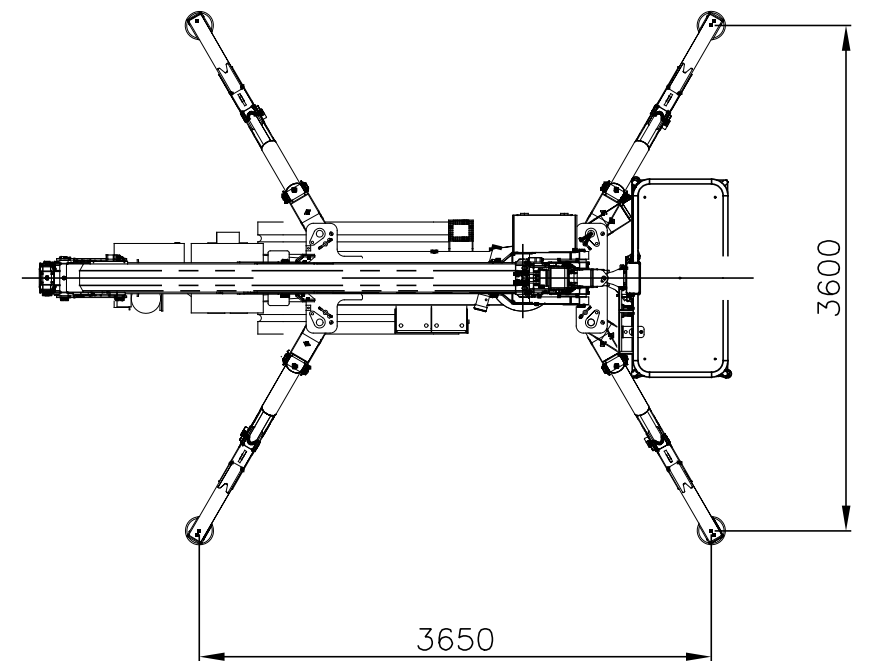
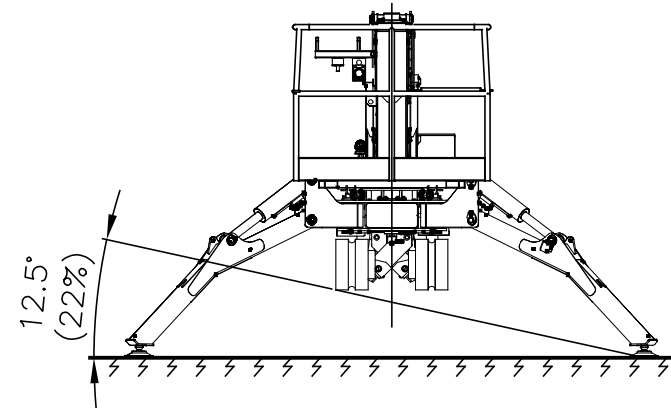
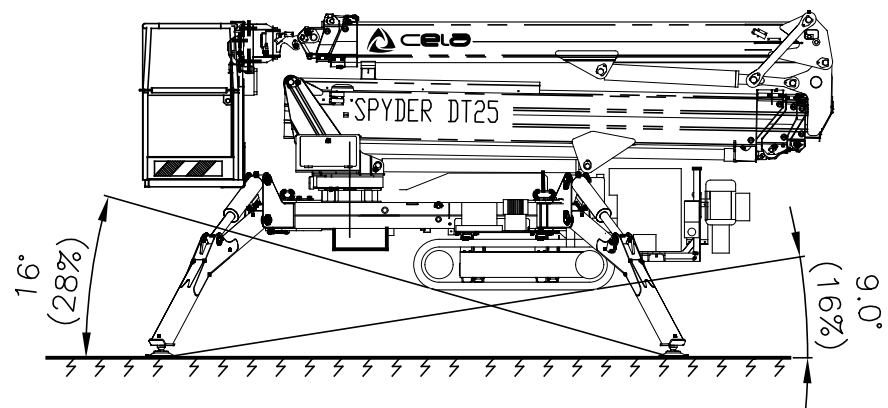
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PROVISIONAL

DENOMINAZIONE - NAME	DISEGNATO - DRAWN	CONTROLLATO - CHECKED
OUTRIGGER CONFIGURATION	R.F.	T.S.
VEICOLO - CHASSIS	AREA DI LAVORO - WORKING AREA	
TRACK CRAWLER	1005702	
PIATTAFORMA - PLATFORM MODEL	P.T.T. - G.V.W.	
SPYDER DT25	2.95T	
		DISEGNO N° - DRAWING N°
		1005701



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PROVISIONAL



DENOMINAZIONE - NAME		DISegnato - DRAWN	CONTrollato - CHECKED
OUTRIGGER CONFIGURATION		S.D.	T.S
VEICOLO - CHASSIS		AREA DI LAVORO - WORKING AREA	
TRACK CRAWLER		—	
PIATTAFORMA - PLATFORM MODEL	P.T.T. - G.V.W.	DISEGNO N° - DRAWING N°	
SPY DT 25	2.9T	1006507	