VIM-303 Vision Guidance System





VIM-303 is a ground breaking 3D vision guidance system that directly controls robotic arms and attached end effectors for pick and place, assembly, machine tending, inspection, and other vision guidance applications.

VIM-303 combines a 3D camera, a high resolution 2D camera, illumination, and embedded high performance vision processing and robot guidance into one compact package.

 $Vision-in-Motion^{TM}$ technology, developed by Visual Robotics, enables tracking and picking of moving objects without a conveyor encoder.

Global shutter stereo cameras, a 12MP color autofocus camera, pulsed LED illumination, active stereo IR projectors, Gigabit Ethernet with PoE, powerful video processing with the Movidius Myriad X, and on-board robot control provide a high-performance industrial solution, designed for robotics.

Powerful object detectors (finders) locate objects based on their 3D shape and dimensions, or by matching the object to a reference image (template matching). Images from the high-resolution color camera can be used to read barcodes, inspect for defects, or measure features.

- 3D Camera
- 2D Camera
- Illumination
- Vision Processing
- Robot Control

In one compact package

VIM-303 incorporates semlessly with the Universal Robots brand of robot arms. The included UR Cap adds vision guidance capability to the native PolyScope graphical programming environment. More complex functionality is possible using the XML-RPC API, allowing users to program in Python, C++ or Java. Users new to robotics can use our no-code programming method with *QuickPick-303* using Blockly.



Sample Object Detection



Rear View, showing mounting and M12 Ethernet

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Specifications

| 3D Camera | | |
|-------------------|-------------------------|-------------|
| Technology | Active Stereo | |
| Resolution | 1280 x 800 (1 Med | gapixel) |
| Frame Rate | 60 FPS | |
| Туре | Monochrome Glo | bal Shutter |
| Focus | Fixed Focus 2.8mm f/2.8 | |
| Field of View | 75° x 51° | |
| Monocular DOF | 80 mm – Infinity | |
| | Near Field | Far Field |
| Working Range | 240 mm | 2,000 mm |
| Lateral Precision | 0.6 mm | 5 mm |
| Depth Precision | 1 mm | 20 mm |

| 2D Color Autofocus Camera | |
|---------------------------|----------------------------|
| Resolution | 4056 x 3040 (12 Megapixel) |
| Frame Rate | 30 FPS |
| Туре | Color Rolling Shutter |
| Focus | Auto Focus 4.52 mm f/2.0 |
| Field of View | 69° x 54° |
| Depth of Field | 80 mm - Infinity |
| Precision | 0.05 mm at 80 mm |

| Illumination | |
|-------------------|------------------------------------|
| Ring Light | Integrated uniform light source |
| | Diffuse white LED ring |
| | Pulsed to freeze motion |
| | 4 independently activatable zones |
| | Ideal for glare reduction |
| Texture Projector | Provides texture for active stereo |
| | 850 nm Class 1 IR laser |
| | DOE 71° x 51° FWHM 11,000 dots |
| | Pulsed to freeze motion |

| Processing | |
|------------------|----------------------------------|
| Vision Processor | Movidius Myriad X VPU |
| | Total processing power 4 TOPS |
| | Neural Compute Engine 1 TOPS |
| | Stereo Depth Correlation Engine |
| | 16 SHAVE processors (GPU) |
| | 500MB on-board LPDDR3 DRAM |
| | YOLOv6-N (416x416) at 65 FPS |
| Core Processor | Quad core 1.5GHz ARM Cortex-A72 |
| | 1GB - 8GB on-board DRAM |
| | 32GB non-volatile flash memory |
| IMU | 6 axis Inertial Measurement Unit |
| Interface | Gigabit Ethernet |
| Operating System | Linux |

| Electrical | |
|-------------------|---------------------------|
| Power | Power over Ethernet (PoE) |
| PoE Class | 802.3at Type 2 Class 4 |
| Power Consumption | < 15 Watts |
| Emissions | FCC Class B |

| Mechanical | |
|------------|-------------------------|
| Size | 125.5 x 57.5 x 56.8 mm |
| Weight | 485 grams |
| Connector | M12 Industrial Ethernet |
| Mounting | Rear or Tripod Mount |
| IP Rating | IP65/67 |

| Image Control | |
|----------------------|--------------------------------|
| Illumination Control | Brightness |
| | Illumination Ring Zones |
| | Texture Projector |
| Camera Control | Resolution |
| | Exposure |
| | Focus |
| Image Outputs | - 2D (high resolution color) |
| | - 3D Depth |
| | - Images time synchronized and |
| | stamped with camera position |

| Object Detection "Finders" | |
|----------------------------|------------------------------|
| Depth | Match object's 3D dimensions |
| Template | Match features in an image |
| | Single image template |

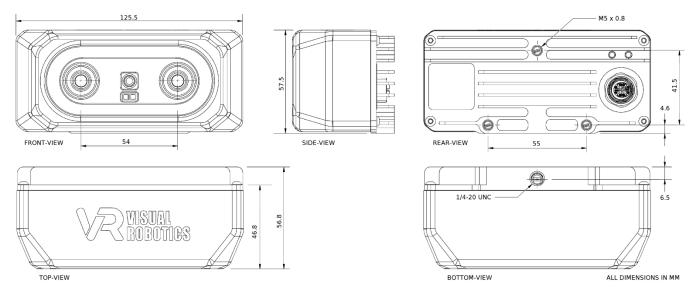
| Tracking and Robot Control | |
|----------------------------|------------------------------------|
| Object Motion | Stationary |
| | Constant Speed |
| | Arbitrary Motion |
| Method | Tracks objects visually within FOV |
| | without conveyor encoder |
| Object Speed (max) | 500 mm/s |
| Typical Applications | Depalletizing |
| | Palletizing |
| | Conveyor Picking |
| | Sorting |
| | Boxing |
| | Kitting |
| | Assembly |

| User Interface and Programming | |
|--------------------------------|-----------------------------|
| User Interface | PolyScope with UR Cap |
| | Web Interface QuickPick-303 |
| Programming | PolyScope |
| | Blockly |
| | XML-RPC (Python, C++, Java) |

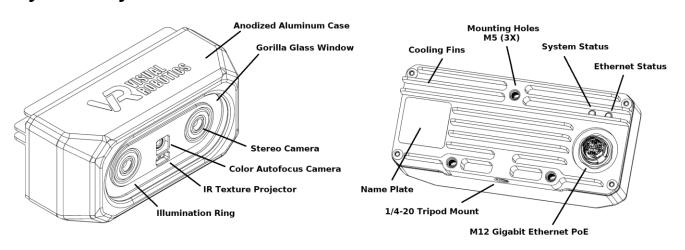
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Dimensions



Physical Layout



Accessories

A 5m high-flex M12-RJ45 Gigabit Ethernet Cable is available standard. Other cable lengths available upon request. Mounts are available for supported robots.



Ethernet Cable

Camera Mount