



AI agents built for the wireless networks physical AI depends on



✦ AI-native design, validation and monitoring

📶 Technology & vendor agnostic

🏠 In-building and outdoors

THE PROBLEM

New machines, new traffic, new QoS requirements.

3.4M

robots shipped per year by 2030
ABI RESEARCH, 2026

10×

more data from physical AI than all AI apps combined by 2029
GARTNER, 2026

200ms

of delay can be enough to put workers at risk around robots
CIO.COM, 2026

A fleet drives the same routes hundreds of times per shift. Most robots need a steady connection the whole way. A wireless network designed for people with handhelds and scanners fails physical AI in three places:

Coverage along the route

Nobody fixes a weak spot that people never notice. A robot drives through it on every pass, with its antenna at knee height behind a steel chassis.

Handovers in motion

On Wi-Fi the client decides when to roam, and robots often hang on too long. A 200 ms gap that a barcode scan never notices can stop a robot mid-route or leave a remote operator driving blind.

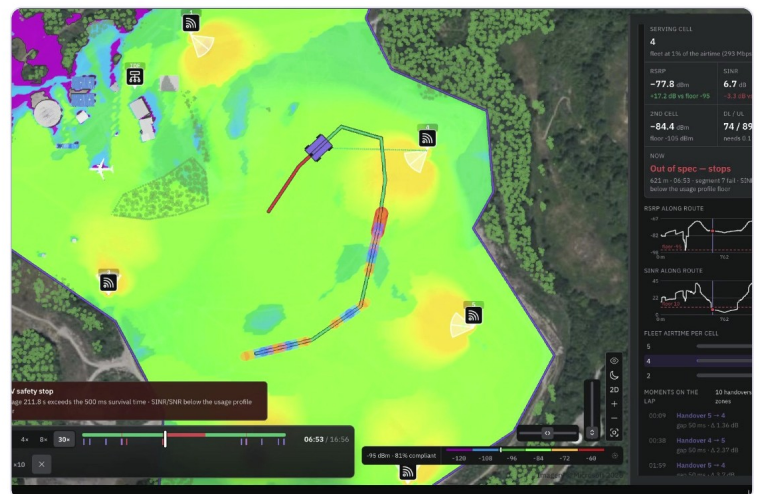
Capacity for the whole fleet

Handhelds send small bursts. Robots send telemetry nonstop, often with video, and bunch up at the same docks and chargers, so one AP can end up carrying much of the fleet at once.

ROUTE QOS

Uncover wireless gaps, before your fleet does.

- 01 **Draw** the route in your digital twin and set what the machine needs from the network: telemetry, video or teleoperation.
- 02 **Simulate** at your real fleet size and speed.
- 03 **Find** every failure to the meter, along with its cause: a coverage gap or a handover problem, each with its own fix.



WHY EINO IS DIFFERENT FROM LEGACY TOOLS

AI-native, cloud-based, and multi-player.

01 One platform, Day 0 to Day 2.

Design, validation and monitoring share one project. Your data layer is exportable and connected across the network lifecycle

02 Every technology in one model.

Wi-Fi, private and public cellular, DAS, public safety, fixed wireless and IoT, indoor and outdoor. Most tools stop at one.

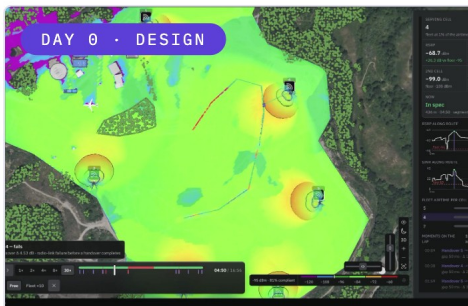
03 Built for speed and collaboration.

GPU-accelerated ray tracing turns a large site rendering around in minutes, in the browser with no install. OEMs, integrators, and enterprise teams work together in one project, seamlessly.

YOUR PHYSICAL AI USE-CASES

Design. Validate. Monitor.

ONE TWIN · DAY 0 TO DAY 2



Design.

Score every route before you install anything.

Add the routes your robots and AGVs will drive, and eino checks each one for coverage, handovers and capacity. Plan Wi-Fi, private cellular, DAS, public safety and fixed wireless together in a 3D twin built from a floor plan or satellite and terrain data. The bill of materials and cost estimate come straight from the design.



Validate.

Measure Wi-Fi and cellular in one walk.

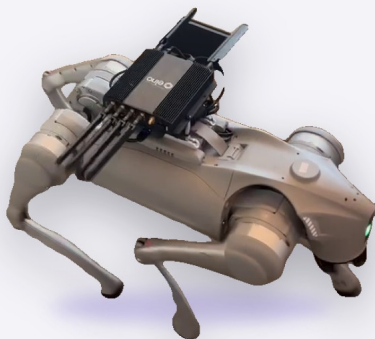
Walk the routes with the eino Site Survey backpack while the companion app captures a 3D model. It measures both in a single pass and puts the results beside the design, so you can see where the site and the plan disagree. Then lift the probe out, power it on PoE+ or DC, and leave it on site to keep testing.



Monitor.

Your agent catches drift from the design before it stops the fleet.

Probes left around the site compare live performance against the design. When something degrades, eino's agents tell you where, why and how confident they are, not just that something went wrong.



AGENTIC NETOPS

Your four-legged wireless engineer

A robot wireless operations engineer for any site.

Remotely controlled, it carries the Site Survey kit along the routes your fleet will drive, runs tests as it walks and emulates different use-cases while it surveys. so the twin is measured from where the robots will actually be.

- Remotely controlled
- Supports WiFi, Private Cellular, DAS, Public Cellular
- Emulates use-cases including walking AGV routes